Table of Contents

Mobile 3D LiDAR-based Object and Change Detection in Production and Operations Management 1
Taru Hakanen, Paul Kemppi, and Petri Tikka

Simulated Ant-agent Aspects for Defining an Ant-bots Ontology 8
Colin Chibaya, Ntshuxeko Chibaya, and Rifilwe Modiba

Toward Autonomous Cardiac Catheterization Through a Parametric Finite Element Simulation With Experimental Validation 14
Majid Roshanfar, Pedram Fekri, and Javad Dargahi

Multi-Agent Planning Method Using Affordances from Environment 19
Sawako Tajima, Daiki Takamura, Daiki Shimokawa, Reo Kobayashi, Reo Abe, and Satoshi Kurihara

A Multi-modal AI Approach For AGVs: A Case Study On Warehouse Automated Inventory 25
Ferran Gebelli Guinjoan, Matthias Hutsebaut-Buysse, Gorjan Radevski, Hugo Van Hamme, Erwin Rademakers, Abdellatif Bey Temsamani, Kevin Mets, Tom De Schepper, Steven Latre, Erik Mannens, and Tinne Tuytelaars

Moderate Loads Handling & Transportation by COBOTs and AMRs: Discussion of Different Architectures to Increase Payload & Reach and to Improve Operators Ergonomics 34
Abdellatif Bey Temsamani, Luka Ramaekers, Wilm Decre, Erwin Aertbelien, Frederico Ulloa Rios, Raphael Furnemont, Karel Van der Elst, Jonas Vantilt, and Joris De Schutter

Matlab/Simulink-Based Modeling for Industrial Electric Vehicle 43
Mouna Samaali, El-Hassane Aglzim, Xavier Dessertenne, and Patrick Dubreuille

Utilizing Continuous Kernels for Processing Irregularly and Inconsistently Sampled Data With Position-Dependent Features 49
Birk Martin Magnussen, Claudius Stern, and Bernhard Sick