

ICAS 2026

Foreword

The Twenty-Second International Conference on Autonomic and Autonomous Systems (ICAS 2026), held between March 8 - 12, 2026, was a multi-track event covering related topics on theory and practice on systems automation, autonomous systems and autonomic computing.

The main tracks referred to the general concepts of systems automation, and methodologies and techniques for designing, implementing and deploying autonomous systems. The next tracks developed around design and deployment of context-aware networks, services and applications, and the design and management of self-behavioral networks and services. We also considered monitoring, control, and management of autonomous self-aware and context-aware systems and topics dedicated to specific autonomous entities, namely, satellite systems, nomadic code systems, mobile networks, and robots. It has been recognized that modeling (in all forms this activity is known) is the fundamental for autonomous subsystems, as both managed and management entities must communicate and understand each other. Small-scale and large-scale virtualization and model-driven architecture, as well as management challenges in such architectures are considered. Autonomic features and autonomy requires a fundamental theory behind and solid control mechanisms. These topics gave credit to specific advanced practical and theoretical aspects that allow subsystem to expose complex behavior. We aimed to expose specific advancements on theory and tool in supporting advanced autonomous systems. Domain case studies (policy, mobility, survivability, privacy, etc.) and specific technology (wireless, wireline, optical, e-commerce, banking, etc.) case studies were targeted. A special track on mobile environments was indented to cover examples and aspects from mobile systems, networks, codes, and robotics.

Pervasive services and mobile computing are emerging as the next computing paradigm in which infrastructure and services are seamlessly available anywhere, anytime, and in any format. This move to a mobile and pervasive environment raises new opportunities and demands on the underlying systems. In particular, they need to be adaptive, self-adaptive, and context-aware.

Adaptive and self-management context-aware systems are difficult to create, they must be able to understand context information and dynamically change their behavior at runtime according to the context. Context information can include the user location, his preferences, his activities, the environmental conditions and the availability of computing and communication resources. Dynamic reconfiguration of the context-aware systems can generate inconsistencies as well as integrity problems, and combinatorial explosion of possible variants of these systems with a high degree of variability can introduce great complexity.

Traditionally, user interface design is a knowledge-intensive task complying with specific domains, yet being user friendly. Besides operational requirements, design recommendations refer to standards of the application domain or corporate guidelines.

Commonly, there is a set of general user interface guidelines; the challenge is due to a need for cross-team expertise. Required knowledge differs from one application domain to another, and the core knowledge is subject to constant changes and to individual perception and skills.

Passive approaches allow designers to initiate the search for information in a knowledge-database to make accessible the design information for designers during the design process. Active approaches, e.g., constraints and critics, have been also developed and tested. These mechanisms deliver information (critics) or restrict the design space (constraints) actively, according to the rules and

guidelines. Active and passive approaches are usually combined to capture a useful user interface design.

We take here the opportunity to warmly thank all the members of the ICAS 2026 Technical Program Committee, as well as the numerous reviewers. The creation of such a high quality conference program would not have been possible without their involvement. We also kindly thank all the authors who dedicated much of their time and efforts to contribute to ICAS 2026. We truly believe that, thanks to all these efforts, the final conference program consisted of top quality contributions.

Also, this event could not have been a reality without the support of many individuals, organizations, and sponsors. We are grateful to the members of the ICAS 2026 organizing committee for their help in handling the logistics and for their work to make this professional meeting a success.

We hope that ICAS 2026 was a successful international forum for the exchange of ideas and results between academia and industry and for the promotion of progress in the fields of autonomic and autonomous systems.

We are convinced that the participants found the event useful and communications very open. We also hope that Valencia provided a pleasant environment during the conference and everyone saved some time for exploring this beautiful city.

ICAS 2026 Chairs:

ICAS 2026 Steering Committee

Roy Sterritt, Ulster University, UK

Mark J. Balas, Texas A&M University, USA

Karsten Böhm, Fachhochschule Kufstein, Austria

Jacques Malenfant, Sorbonne Université | LIP6 Lab, France

Claudius Stern, biozoom services GmbH - Kassel | FOM University of Applied Sciences – Essen, Germany

Philippe Martine, INRIA Sophia Antipolis, France

ICAS 2026 Publicity Chairs

Francisco Javier Díaz Blasco, Universitat Politècnica de València, Spain

Ali Ahmad, Universitat Politècnica de València, Spain

Sandra Viciano Tudela, Universitat Politecnica de Valencia, Spain

José Miguel Jiménez, Universitat Politecnica de Valencia, Spain