

## Security Considerations for Multicast Communication in Power Systems

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**Abstract**—Information security is gaining increasingly more importance for real-time automation networks. Multicast communication is used widely especially on field and process level to cope with performance requirements and to ease the handling of communication peers as the destinations need not to be known by the sender. A security design must not interfere with these communication types. This paper investigates into different approaches to achieve multicast security focusing on energy automation networks. Here, domain-specific protocols like GOOSE are used within substations to distribute measurement and status information between IEDs using plain Ethernet superseding classical copper wire connections. Hence, they have to cope with high performance requirements in terms of very low latency and transfer time. For these reasons, a solution is required allowing to perform efficient authentication of field-level multicast communication. Moreover, this multicast authentication may also be applicable in WAN communication, as the substation protocol GOOSE is meanwhile also being applied to exchange synchrophasor data.

**Keywords**—security; device authentication; multicast; real-time; network access authentication; firewall; substation automation; wide area condition monitoring

### I. INTRODUCTION

Decentralized energy generation, e.g., through renewable energy sources like solar cells or wind power, is becoming increasingly important to generate environmentally sustainable energy and thus to reduce greenhouse gases leading to global warming. Introducing decentralized energy generators into the current energy distribution network poses great challenges for energy automation (EA) in a smart grid scenario as decentralized energy generation needs to be monitored and controlled to a similar level as centralized energy generation in power plants while requiring widely distributed communication networks. Distributed energy generators may also be aggregated on a higher level to form a virtual power plant. Such a virtual power plant may be viewed from the outside in a similar way as a common power plant with respect to energy generation. But due to its decentralized nature, the demands on communication necessary to control the virtual power plant are much more challenging. Moreover, these decentralized energy resources may also be used in an autonomous island mode, without any connection to a backend system.

Furthermore, the introduction of controllable loads on residential level requires enhancements to the energy automation communication infrastructure as used today. Clearly, secure communication between a control station and

equipment of users (e.g., decentralized energy generators) as well as with decentralized field equipment must be addressed. Standard communication technologies as Ethernet and IP are increasingly used in energy automation environments down to the field level. Guaranteed real-time communication plays an essential role for many industrial control applications (see also [1], [2]).

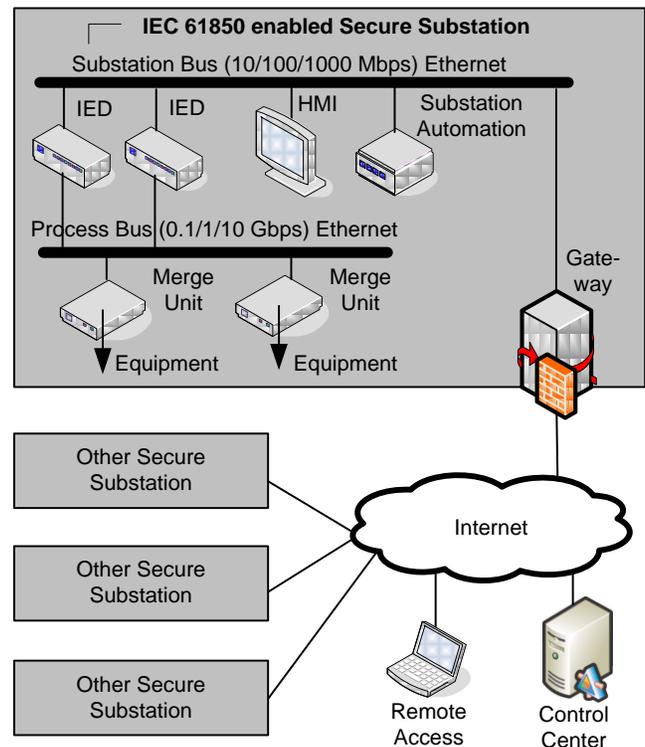


Figure 1. Typical IEC 61850 Scenario

IEC 61850 is a popular standard for communication in the domain of energy automation. It is envisaged to be the successor of the currently used standards IEC 60870-4-104 and DNP3 also for the North American region. IEC 61850 enables interoperability between devices used in energy automation, i.e., two IEC 61850 enabled devices of different manufacturers can exchange a set of clearly defined data and the devices can interpret and use these data to achieve the functionality required by the application due to a standardized data model. In particular, IEC 61850 enables continuous communication from a control station to

decentralized energy generators by using a standardized data format.

Today, IEC 61850 is mainly used for reporting status and sampled value information from Intelligent Electronic Devices (IED) to Substation automation controller as well as for command transport from Substation automation controller to IEDs. It also addresses the communication directly between IEDs using the Generic Object Oriented Substation Event (GOOSE) instead of dedicated wires. Necessary tasks comprise also configuration of equipment as well as control of circuit breakers. Figure 1 shows a typical example scenario in which IEC 61850 can provide a clear benefit (see also [3], [4]).

IT security is increasingly important in energy automation as on part of the Smart Grid. Here, IEC 62351 kicks in, defining security services for IEC 61850 based communication covering different deployment scenarios using serial communication, IP-based communication, and also Ethernet communication. The latter one is used locally with a substation to cope with the high real-time requirements. While these messages may not need to be encrypted to protect confidentiality, they need to be protected against manipulation and to allow for source authentication. Note that besides pure communication security, there is also the need to address security in the physical environment and also in the organizational processes. This is typically addressed in the context of IEC 27001 [5] describing the Information Security Management Standard (ISMS). While this standard targets general applicability, there exist domain specific mappings of the related ISO 27002 [6] best practice guidelines which are applicable for the automation domain. Relevant are in particular ISO TR 27019 [7] for energy automation and IEC 62443-2-1 (ISA 99.2.1) [8] for industrial automation. Both standards are mentioned here to underline that security is not restricted to the field communication, but applies to the embedding environment as well. However, this paper concentrates on the specific problem of multicast authentication on field level.

The remainder of this paper is structured as follows: Section II provides an overview on real-time control networks with the example of the GOOSE substation automation protocol. Section III maps GOOSE to wide area monitoring. Section IV describes the problem statement and the existing security solution as defined in the standard. Section V gives an overview about multicast authentication schemes in general. This is used later on in Section VI and Section VII by applying them to substation automation protocols. Section VIII concludes the paper and provides an outlook.

## II. SUBSTATION AUTOMATION COMMUNICATION

Real-time systems typically consist of hardware and software that are subject to time constraints regarding execution of commands. This comprises the initiation of a command, the execution itself and the acknowledgement of the execution. Real-time in the context of this paper refers to systems with a deterministic behavior, resulting in a predictable maximum response time. These systems will

handle all events at appropriate (context-dependent) speed, without loss of events.

Automation networks are typically shared networks connected in a ring, star, or bus topology or a mixture of these. Most often, the time critical part is realized on a dedicated network segment, while the rest of the communication supporting the automation systems is performed on networks with lower performance requirements.

An example for energy automation is the communication within a substation. A substation typically transforms voltage levels, and includes power monitoring and protection functions. In the example shown in Figure 2, the communication of the protection devices is separated from the historian data (stored in the historian device, see Figure 2 in below) in a separate network zone of the substation. The historian data may even be sent to a SCADA (supervisory control and data acquisition) or office network. The historian is a device for archiving measurements, events, and alarms of the substation.

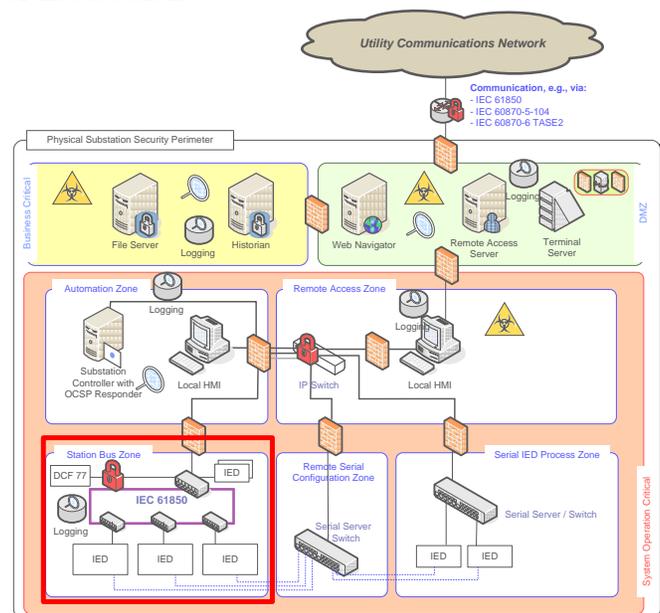


Figure 2. Substation – Functional Split into Zones

As depicted in Figure 2, the substation bus can be realized as ring, connecting the protection relays, acting in real-time. There is a connection to other zones within the substation, separated from the real-time part using Firewalls. Examples are the automation zone or the remote access zone. Another example is the zone storing the historian information also interacting with a backend SCADA system. Figure 2 already shows security elements deployed within a substation, like Firewalls, virus checking tools, or access control means to components or data.

Figure 3 shows a ring topology used to connect field devices in the process bus zone. Besides the field devices, which may be protection devices exchanging information about the current state of the measured values with respect to voltage or current, also controllers are likely to be available. These controllers provide the connectivity to other bays in a

substation or to a control center, relying on the operation of the protection devices but also on the measurement data to counter certain electric effects.

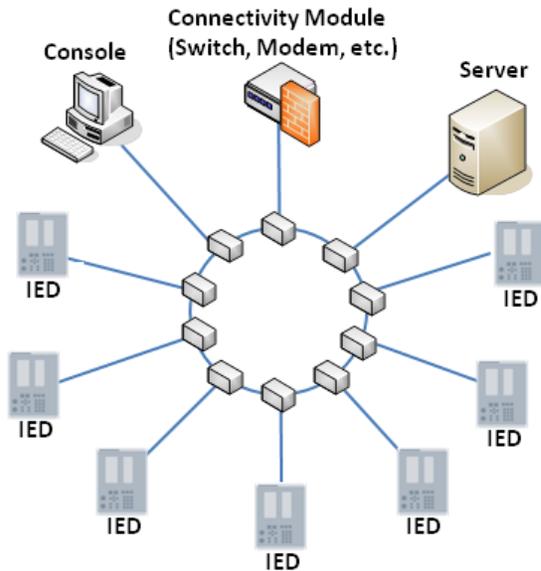


Figure 3. Ring topology in a substation

One of the protocol sets used in substation automation is IEC 61850, which provides Generic Object Oriented Substation Events (GOOSE) on process bus level. It is a control model mechanism in which any format of data (status, value) is grouped into a data set and transmitted as set of substation events, such as commands, alarms, or indications. It aims to replace the conventional hardwired logic necessary for intra-IED (Intelligent Electronic Device) coordination with station bus communications. Upon detecting an event, field devices use a multi-cast transmission to notify those devices that have registered (subscribed) to receive the data (see also Figure 4). GOOSE messages or Sampled Values (SV) are re-transmitted multiple times by each field device. The reaction of each receiver depends on its configuration and functionality. Note that the registration to events is purely device local at the receiver side. This results in the fact that the sender does not know the receiver of its GOOSE message sent.

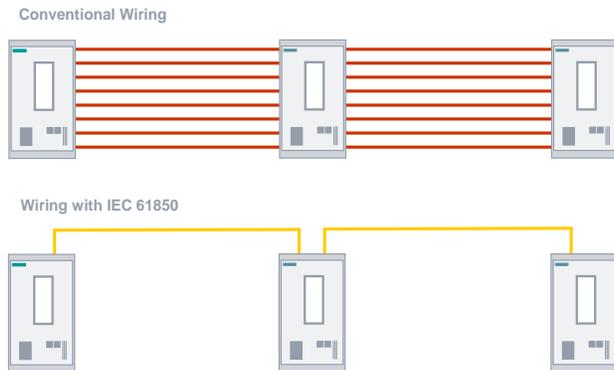


Figure 4. Advantage of using IEC 61850 GOOSE

Following mechanisms are used to ensure the required transmission speed and reliability:

- GOOSE data is directly embedded into Ethernet data packets and works on publisher-subscriber mechanism on multicast or broadcast MAC addresses.
- GOOSE uses VLAN and priority tagging as per IEEE 802.1Q to have a separate virtual network within the same physical network and to set an appropriate message priority level.
- Enhanced retransmission mechanisms – the same GOOSE message is retransmitted with varying and increasing re-transmission intervals. A new event occurring within any GOOSE dataset element will result in the existing GOOSE retransmission message being stopped. A state number within the GOOSE protocol identifies whether a GOOSE message is a new message or a retransmitted message.

IEC 61850-5 [3] defines message types and their performance classes. The following performance classes are supported:

- P1 typically applies to a distribution bay (or where low requirements can be accepted),
- P2 typically applies to a transmission bay (or if not otherwise specified by the customer),
- P3 typically applies to a top performance transmission bay.

Table I below shows the different message types and their timing requirements based on IEC 61850-5 [3].

TABLE I. GOOSE TRANSFER TIMES

Type	Definition	Timing Requirements
1	<b>Fast messages</b> contain a simple binary code containing data, command or simple message, examples are: "Trip", "Close", etc.	See Type 1a and 1 b below
1A	<b>TRIP</b> – most important message	<ul style="list-style-type: none"> <li>- P1: transfer time shall be in the order of half a cycle. → 10 ms</li> <li>- P2/3: transfer time shall be below the order of a quarter of a cycle. → 3 ms</li> </ul>
1B	<b>OTHER</b> – Important for the interaction of the automation system with the process but have less demanding requirements than trip.	<ul style="list-style-type: none"> <li>- P1: transfer time &lt; 100ms</li> <li>- P2/3: transfer time shall be below the order of one cycle. → 20 ms</li> </ul>
2	<b>Medium speed messages</b> are messages where the time at which the message originated is important but where the transmission time is less critical.	<ul style="list-style-type: none"> <li>- Transfer time &lt; 100ms</li> </ul>
3	<b>Low speed messages</b> are used for slow speed auto-control functions, transmission of event records, reading or changing set-point values and general presentation of system data.	<ul style="list-style-type: none"> <li>- Transfer time &lt; 500ms</li> </ul>

The definition of transfer time, according to IEC 61850-5, is shown in Figure 5 below. The transfer time includes the complete transmission of a message including necessary handling at both ends. The time counts from the moment the sender feeds the data content into transmission stack till the moment the receiver extracts the data from its transmission stack. As shown in Table I, the transfer time of GOOSE messaging for a TRIP command shall be such that the command should arrive at the destination IED within 3ms.

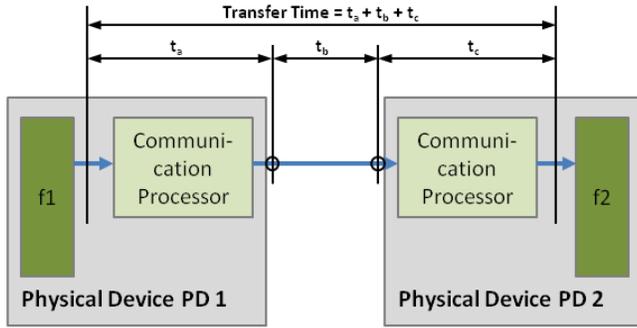


Figure 5. Transfer Time [3]

For a single IED, by assuming the time for the publishing process  $t_a$  and the subscribing process  $t_c$  are approximately equal and if  $t_b$  (network transfer time) can practically be ignored, then at least half of the defined time is needed for the IEDs to process the message (i.e., 1.5ms for a TRIP

message). As shown in Figure 6, if a signal as, e.g., the pick-up "Overcurrent  $I > \text{picked up}$ ", is configured in a GOOSE message, the IED sends this message cyclically every 0.5 seconds as a telegram with high priority over the Ethernet network. The content of this telegram communicates the state of pick-up ("not picked up" or "picked up") to the subscribers of the GOOSE message. The cyclic transmission enables each of the subscribers to detect a failure using a logic block when a transmitter has failed or a communications channel has been interrupted.

This approach provides constant monitoring of the transmission line because the subscriber expects to receive a telegram at several-second intervals. This can be compared with pilot-wire monitoring in conventional wiring. On a pick-up, i.e., a signal change, a GOOSE telegram is transmitted spontaneously and is repeated after 1 ms, 2 ms, 4 ms etc. before returning to cyclic operation.

Typical examples for GOOSE application in substation automation comprise:

- Tripping of switchgear
- Starting of disturbance recorder ("Störschrieb")
- Providing position status of interlocking

Security requirements and solutions for GOOSE communication have already been specified. They are discussed as part of Section IV.

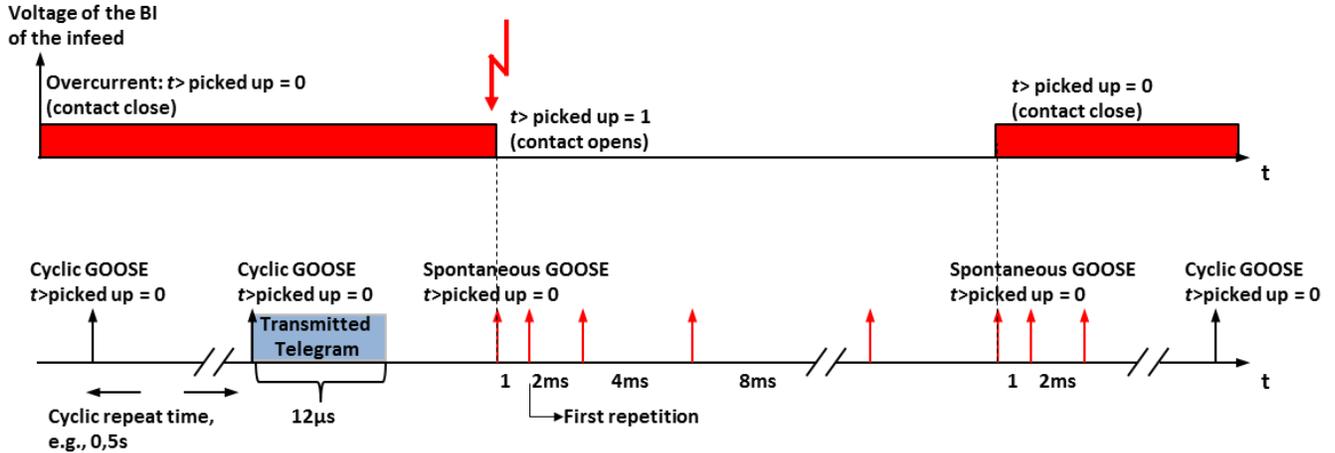


Figure 6. Transmission of binary states with GOOSE messages

### III. WIDE AREA STATUS MONITORING

Besides the application of GOOSE and SV communication within a substation, there is also the need to transmit status and power measurements as synchronized status information over wide area networks. One driver of this is the request to be able to detect frequency deviations from widely dispersed areas very early and act accordingly to prevent blackouts. Examples are:

- The blackout in the North America northeastern in 2003, affecting more than 50 million people in the US and Canada [9].
- The blackout in India in 2012 was the biggest blackout so far. The power outage affected more than 620 million people [10].

Further information about major blackouts can be found in [11]. It is clear that not all of these blackouts can be prevented, but supporting wide area measurement and protection and control (WAMPAC) may certainly be used to identify the risk of a blackout. This information in turn can then be used to apply proper counter measures in time and to reduce of spreading of the blackout.

This is addressed in the technical report IEC 61850-90-5 [12] describing the use of GOOSE and SV over wide area networks. Note that Ethernet will not be the base for communication in these scenarios but UDP/IP, which also allows for multicast, e.g., of synchrophasor measurement unit data.

The security approach described for wide area usage of GOOSE and SV will also be fed into the further enhancement of IEC 62351. Specifically, the Internet group key management protocol GDOI [13] will be the bases for the key management standard IEC 62351-9, while the application of the group key will be described in an edition 2 of IEC 62351-6. Both documents are currently work in progress.

### IV. SECURITY FOR SUBSTATION AUTOMATION MULTICAST MESSAGES

Security is a basic requirement for protecting substation automation communication. The main security requirements especially for GOOSE and SV communication have been determined as message integrity and source authentication.

Within the standard IEC 62351-6, a security solution is provided that exactly addresses these requirements for the transfer of GOOSE and SV messages in multicast Ethernet networks. The basic approach builds on digital signatures. They are used to calculate a cryptographic checksum over the payload of the Ethernet PDU (Protocol Data Unit). The transport of the security related part is defined as an extension to the existing definition of the GOOSE or SV PDU. Digital signature calculation requires a high computational load to the IED, especially if retransmissions are taken into account. Retransmissions require a new signing operation to avoid potential replay attacks by simply repeatedly sending signed packets. Moreover, at a sample rate of 80 samples per power cycle, up to 4000 packets per second have to be signed for the common power frequency

of 50 Hz. If each of those messages is protected by a digital signature, a high computational burden is placed on the sender by the generation of the digital signatures, and also on the receiver for verifying the signature. IEDs are typically not built to handle this type of operation at that speed. This has been verified by prototypes running on FPGAs [14]. Therefore, there exists a demand for an alternative solution to address the security requirements for protected communication more efficiently [15].

As stated in the previous section, there exists also a demand to transmit Phasor Measurement information in distributed environments over wide area networks. A new requirement arising here is the confidentiality of the data. This requirement stems from the fact that the synchrophasor information may be misused by an eavesdropper to determine the current load and stability of a dedicated electricity network. While this information is protected in a substation by physical means, it needs to be protected when communication over wide area networks based on sound cryptographic methods. Note that the discussion of confidentiality is not part of this paper.

To better cope with the required performance, IEC 61850-90-5 proposes to rely on integrity check values (ICV), which are calculated using HMAC-SHA256 or AES-GMAC involving a shared key, rather than using digital signatures. This shared key is supposed to be a group based key, shared among the configured participants of a group. A key distribution center is responsible for authenticating the group participants and generating and distributing the shared group key to authenticated peers.

The underlying key distribution protocols is Group Domain of Interpretation GDOI, [13]. It has already proven its practical feasibility in many IP router implementations to distribute group keys for multicast services in the Internet. The integrity check is applied in the processing in a similar way as the digital signature. The sender creates the ICV, while the receiver checks the ICV upon receiving the message, before executing a command.

The following subsections discuss multicast authentication options in general and propose the application of authentication schemes for dedicated messages that allow for the delayed verification of message integrity of already received messages.

### V. EXISTING APPROACHES FOR MULTICAST AUTHENTICATION

Many widely used security protocols as IPSec [4] and SSL/TLS [17] are designed mainly for point-to-point communication. However, the communication type of multicast requires specific handling. The objective of security within substation automation is to ensure the integrity and authenticity of messages. Protecting the confidentiality is not required, however.

Figure 7 shows the basic set-up. A sender sends a message containing data protected with a message authentication code MAC. Several receivers verify the received message. Cryptographic authentication of multicast communication comprises to main parts:

- Message protection: A data packet or frame has to be protected (encryption and/or message authentication). A cryptographic checksum (message authentication code) is applied to a message that is verified by the receivers.
- Multicast Key management: The cryptographic keys required by the sender and by the receiver have to be established.

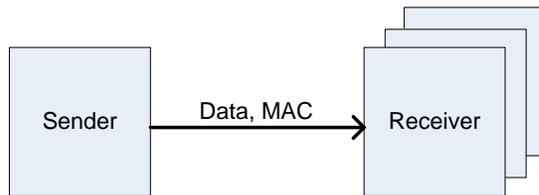


Figure 7. Broadcast/Multicast Sender Authentication

Conceptually, the problem would be solved by applying a digital signature scheme, e.g., PKCS#7 [18], based on public key cryptography, e.g., RSA [19], DSA [19], or ECC-based signatures [19]. However, the computational requirements of these algorithms render them inadequate for the targeted field level devices as already discussed in Section IV above. So a message level protection based on symmetric algorithms as AES-CBC-MAC, AES-GMAC, or HMAC-SHA256 [19] is used. The sender and the receiving nodes apply the same secret key for creating and for verifying the cryptographic checksum.

The following subsections discuss potential approaches for message protection as well as options for key management.

#### A. Delayed Authentication of Multicast Messages

The Timed Efficient Stream Loss-tolerant Authentication protocol (TESLA) [20] provides sender authentication. TESLA is based on loose time synchronization between the sender and the receivers. Source authentication is realized in TESLA by using Message Authentication Code (MAC) [19] using a symmetric key of a one-way key chain.

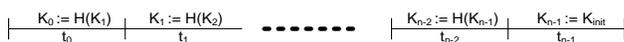


Figure 8. Hash Key Chain

Figure 8 illustrates the concept of a hash key chain. The hash key chain of length  $n$  is determined by the sender starting with a randomly chosen key  $K_{init}$  that is valid during a time period  $t_{n-1}$ . The sender computes the keys  $K_i$  using a cryptographic hash function  $H$  as the hash of the key  $K_{i+1}$ , i.e.,  $K_i := H(K_{i+1})$ . The key  $K_i$  is valid for sending messages only during the time period  $t_i$ . But the sender releases the key  $K_i$  only after the time period  $t_i$  has already passed, i.e., when the key is not valid for sending anymore. A receiver can verify messages received during the time period  $t_i$  only after  $t_i$  has passed, i.e., after having received the key. However, a malicious receiver cannot forge messages on behalf of the sender as the key is already invalid.

The sender provides the first key  $K_0$  to receivers in a secure way (i.e., protected by a digital signature or provided over a protected communication channel). Each receiving

node stores the key  $K_0$ . Further keys  $K_{i+1}$  are released by the sender in clear as a receiver can verify the authenticity of the released key efficiently by computing its hash value. Due to the one-way property of the hash function  $H$ , a receiver cannot practically determine a key  $K_{i+1}$  from a known  $K_i$ .

The important property of the one-way key chain is that once the receiver has obtained a single authenticated key of the chain, subsequent keys of the chain are self-authenticating. This means that the receiver can easily and efficiently authenticate subsequent keys of the one-way key chain using the one authenticated key. The initially distributed message is protected using a well-known digital signature.

$\mu$ TESLA addresses sensor network scenarios and optimizes the TESLA protocol for this use case [15]. The general setup assumes a base station, which has an authenticated connection to sensor nodes based on a shared secret. As the digital signature for the initial message protection in TESLA is too costly for sensor nodes,  $\mu$ TESLA addresses this by using the node-to-base-station authenticated channel to bootstrap the authenticated broadcast. The remainder of the protocol is similar to the original TESLA approach.

#### B. Group based Key Management

Various protocols have been designed for group key management, e.g., the Group Key Management Protocol (GKMP) [21] and Scalable Multicast Key Distribution [22]. Group Secure Association Key Management Protocol (GSAKMP) [23]. A survey [24] of group key management protocols describes different options for group key management in centralized environments. Also common wireless communication standards support secure multicast/broadcast communication, e.g., IEEE 802.11 WLAN [25] and 3GPP Multimedia Broadcast/Multicast Service [26].

The basic design idea is to rely on a group key management server that authenticates group members and establishes group keys for protecting communication within the group. There exist also decentralized approaches for group key establishment that do not require a group key server, e.g., Group Diffie-Hellman Key Exchange [27].

All these approaches result in a symmetric group key shared between the members of the group. So each node can send and verify protected group messages. No authentication of the sending node is achieved, as each group member knows the group key that can be used for both sending and receiving messages. In contrast to group based key management in volatile environments like video conferences or similar, a join and leave policy is likely not be needed in energy environments. This join and leave policy typically ensures that whenever a group member joins or leaves a group a fresh key is distributed. This is being done to avoid that even a regular group member can eavesdrop the communication of his associated group when he is not participating in a group session. This requirement is not obvious in energy automation as the networks are rather static and engineered at a certain point in time, according to a fixed required functionality.

A specific key management based on key chains can be used to achieve sender authentication with symmetric cryptography. An element of the key chain is valid for sending only during a limited, defined time period. During that time period, it is known only by the sender. Only after the time validity has passed, the key is revealed to receiving nodes. To verify a received message, a receiving node has to store the received message until it has received the corresponding key. Only after receiving also the key, the receiver can verify the received messages. This leads to a delay in processing of the messages. The approach in general has been described in subsection V.A by using TESLA as one example. The following subsection elaborate more on selected group key management protocols frameworks.

1) *Group Domain of Interpretation (GDOI)*

GDOI is the result of the IETF multicast security working group and is defined in RFC 6407 [13]. It defines an architecture where a group controller manages the key material and the connected policies for a defined group. The group members typically authenticate towards the group controller before they are allowed to participate in the group. GDOI allows for pull and push distribution of the group key material and also allows for the update of this information. The difference between the two modes push and pull is mainly who initiates the key distribution, the group controller or the client. For application within IEC 61850-90-5 the focus is placed on the pull mechanism. Also, a key update is performed by simply reauthenticating towards the group controller.

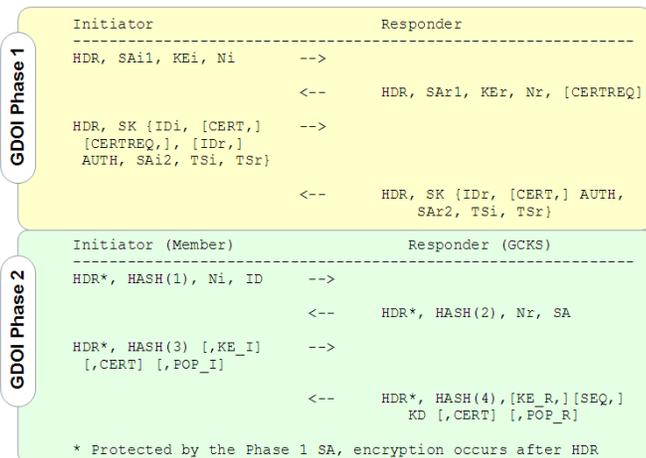


Figure 9. GDOI Call Flow

Figure 9 shows the messages and their content for the general call flow of GDOI. While the first phase basically resembles an Internet Security Association and Key Management Protocol (ISAKMP) phase 1 key exchange to authenticate both peers and establish security associations (SA), the second phase is used to realize the GDOI PULL registration or PUSH rekey exchange. Within its application in IEC 61850 environments, always the PULL method is used. Even in the case of rekeying, the client connects to the group key server and authenticates and then receives the new

group key. This approach has been chosen to ensure that clients in the network authenticate towards the group key server. The “join-and-leave” behavior, e.g., in multimedia communication is not pertained as the configuration of groups in the energy environment is rather static. Joining and leaving of members of a group leads to updates of the group key otherwise, to ensure that a new participant gets now information about previous exchanges and leaving participants cannot eavesdrop the ongoing discussion.

Note that GDOI has been successfully implemented to negotiate key material for protecting router communication using IPSec.

2) *Multimedia Internet Keying (MIKEY)*

MIKEY has been defined in the IETF within RFC3830 [28]. It defines an authentication and key management framework that can be used for real-time applications (both for peer-to-peer communication and group communication). In particular, RFC3830 is defined in a way to support SRTP in the first place but is open to enhancements to be used for other purposes too. MIKEY has been designed to meet the requirements of initiation of secure multimedia sessions. Such requirements are for instance the establishment of the security parameters for the multimedia protocol within one round trip.

Another requirement is the provision of end-to-end keying material, and also independence from any specific security functionality of the underlying transport layers.

MIKEY defines several options for the user authentication and negotiation of the master keys all as maximum as 2 way-handshakes as there are:

- Symmetric key distribution (pre-shared keys, Message Authentication Codes (MAC) for integrity protection; may proceed in a one-way handshake)
- Asymmetric key distribution (based on asymmetric encryption; may proceed in a one-way handshake)
- Diffie Hellman key agreement protected by digital signatures (two-way handshake).

Unprotected key distribution, i.e., without authentication, integrity, or encryption, is also possible, but not recommended without any underlying security like TLS or similar. This use case is comparable with the security description approach described below (see the following section).

VI. ENHANCEMENTS FOR SUBSTATION AUTOMATION MULTICAST SECURITY

In this paper, we propose a new solution for the authentication and integrity protection of broadcast/multicast control messages. It combines hash key chains with digital signatures. This solution can be applied in particular to a field-level energy control protocol (e.g., a substation controller).

To avoid a centralized node as single point of failure each sending node manages its own key chain. As in TESLA, the initialization information of a hash key chain is protected by the sender using a digital signature.

Synchronized time is already available in energy automation using Network Time Protocol (NTP) [29] per substation. A GPS receiver is attached to the substation controller to provide the reference time for all connected components. If a GPS device is not available, the time information may also be received from a hierarchically higher system component like a control center over other signaling channels. Here, NTP may be used to synchronize to a time source in the associated control center.

Known enhancements to the basic TESLA scheme support immediate authentication by using buffering by the sender [30]. However, this requires that the sending node has to already have the information about the contents of future packets. This makes it unsuited for real-time control applications where the future changes in the physical world are not known in advance. Furthermore, the usage of multiple key chains has been proposed where a sending node manages multiple hash chains for receivers observing different network delays.

The following subsections describe new enhancements to TESLA to cope with the specific requirements of a real-time control network.

#### A. Multiple Message-class specific Hash Chains

A sending node manages multiple hash key chains. A hash key chain message is bound to a certain class of control messages. The class of control messages is specified by the sender as part of the hash chain's initialization information. This allows a receiver to determine whether an announced hash chain includes potentially control commands relevant for the receiver. Only if this is the case, the receiver has to store the initialization information. A receiver may also verify that a received control message is in fact of the class as announced in the hash chain initialization information.

#### B. Hierarchical Hash Key Chains

In TESLA, each hash key chain initialization information is protected by a separate digital signature. It is proposed to establish a first hash key chain that is used to protect initialization information of further hash key chains. This is in particular advantageous if several hash key chains are established for different message classes. Also, hash chains which have to be established frequently as they may have a short time delta between hash chain values can be established efficiently.

#### C. Early control command execution

When using a hash chain, a receiver can verify the cryptographic checksum of a received control message only after a certain delay (when the next element of the hash chain is disclosed by the sender). This leads to a non-negligible delay. It is therefore proposed that for some classes of commands the receiver performs the control action immediately after receiving the message, i.e., before verifying the command's cryptographic checksum. However, roll-back information is stored by the receiver. Should the checksum be invalid (once it is verified later), an inverse control operation is performed, neutralizing the effect of the invalid control command. If the checksum is valid, the roll-

back information is deleted to free occupied memory. In an enhancement, this early command execution is performed only for certain control commands, e.g., for which parameter values have passed a plausibility check. The distinguished message handling, based on the type of the control command, allows a receiver to be also more resistant to denial of service attacks, as only dedicated commands are checked immediately. It is also obvious, that for better denial of service protection, additional means are to be provided in the network, to shift load from the IEDs. These means may comprise IDS (Intrusion Detection Systems) or IPS (Intrusion Prevention Systems). The interworking with these systems is outside the scope of this paper.

#### D. Comparison

The properties of the proposed enhancements are evaluated regarding their impact on the field devices. Performance requirements on field level devices are reduced even further as a device processing only data with low rate or with low real time requirements has to process only messages of a corresponding hash key chain. The number of digital signature verifications is kept low as the hash key chain initialization information of the multiple key chains is protected by a hash key chain itself. The design fits with the existing solutions, supporting publish/subscribe communication, and avoiding any central controller. It is one option that can be used in combination with currently defined options.

However, still support for digital signatures is required. This may be avoided by using the  $\mu$ TESLA approach in such cases where a substation controller is available to distribute the initial group key in an authenticated way. Also the time delay caused by the period of uncertainty between reception and verification of a message is still occurring, making it inappropriate for control traffic requiring a very short reaction time (e.g., an emergency power switch off in case of overload). So, there is basically a trade-off whether immediate reaction to a control command is more important than sender authentication. The described approach of defining different security solutions for different message classes allows addressing application-specific side conditions by the security solution. For example, it is possible that a power on command is accepted only with sender authentication, while emergency power off is performed using normal group membership authentication. The susceptibility to denial-of-service attacks is not necessarily increased as control equipment could also provide wrong, manipulated measurements or control command by themselves (independent of any cryptographic authentication scheme).

## VII. INTEGRATION INTO SUBSTATION AUTOMATION PROTOCOLS

The described approach for multicast sender authentication can be integrated in existing field level energy automation protocols transmitting GOOSE or SV information. This is shown in Figure 10 by depicting the initial key chain generation and delayed key distribution.

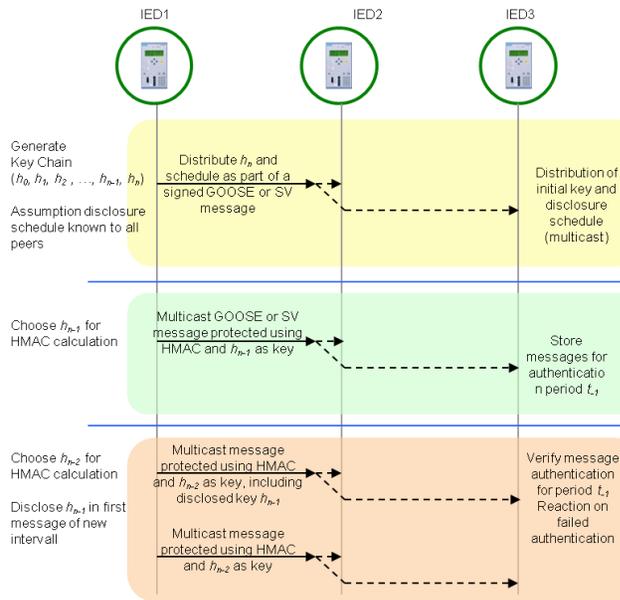


Figure 10. Broadcast/Multicast Control Message Sender Authentication in Field Level Energy Automation

This has the following implications on field level devices:

- Each field device requires a public private key pair to protect the initialization information. The public key is certified and available for other field devices.
- A disclosure schedule is known to all entities upfront, e.g., fixed or defined during engineering.
- The field device has to generate a hash key chain of determined length  $n$  ( $h_0, h_1, h_2, \dots, h_{n-1}$ ). The length is determined by the time interval  $t_A$  that shall be covered by the overall hash key chain. Other factors are the storage requirements of messages at the receiver side. This time interval  $t_A$  is then divided into subintervals  $t_i$ . Each subinterval is associated with a key from the hash chain ( $t_0, h_n, t_1, h_{n-1} \dots t_n, h_0$ ).

The operation proceeds as follows:

- Step 1: Initialization of the Hash Chain by an IED. The field device sending GOOSE or SV broadcast/multicast messages provides the last value of the hash chain as part of a GOOSE or SV message and protects this message before sending it. The field level device uses a digital signature, or a higher-hierarchy hash key chain. The field device includes a description (manifest) of the message type protected with this hash chain. All subscribers will receive the message, and upon successful verification they will store the hash value together with an identifier of the sender. This identifier may be a MAC address, a serial number or similar.
- Step 2: Sending protected broadcast/multicast messages by a field device.

After step 1, the time interval  $t_i$  starts that is associated with the hash value  $h_{n-1}$ . The field device now uses a keyed hash for this time interval to protect the integrity of the GOOSE or SV values. The receiver has to store the messages until the sender has released the hash value  $h_{n-1}$ . This value can be released after the time interval has ended. The value can be released in clear. The receiver can now calculate the integrity check value of the stored message to achieve a delayed authentication of these messages.

An advanced variant of the key disclosure schedule may alternatively depend on the number of messages sent. Another advanced variant of the key disclosure schedule may alternatively depend on the priority (e.g., depending on the performance class) of the message sent.

As shown before, the general approach for protection of the distribution of the initial group key can be followed, allowing for authentication based on digital signatures (as in TESLA or as in IEC 61850-90-5) while the handling of the actual messages is protected using symmetric key application.

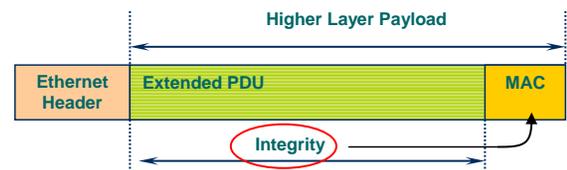


Figure 11. Application of a group key

Figure 11 shows the application of a group based key to provide integrity protection of the higher layer protocol.

### VIII. CONCLUSIONS AND OUTLOOK

This paper described energy automation environments like substation communication where multicast authentication is used. Commands or sampled values are sent via GOOSE as defined in IEC 61850. As shown, the currently specified security mechanisms in IEC 62351-6 to ensure source authentication and message integrity provides for very good security. The flipside is that the application of this approach is hindered by the typical hardware used in IEDs. This hardware is limited and does not cope with performance requirements of the implied cryptographic operations (digital signatures) while matching the time restrictions of the deployment environment.

This paper analyzed various multicast authentication schemes as alternative solutions for the intended use case like digital signatures, GDOI for group key establishment in cooperation with a keyed hash for integrity protection, and TESLA. It investigates specifically the application of TESLA, and mapped the protocol to the substation automation use case. TESLA provides a solution for delayed authentication allowing an IED to perform a dedicated action in real-time and to perform the associated security check later on. It is obvious that there is a period of uncertainty between reception and verification of a message, making it inappropriate for control traffic requiring a very short

reaction time (e.g., an emergency power switch off in case of overload) for actions, which may not be reversible. So, there is basically a trade-off whether immediate reaction to a control command is more important than sender authentication. It is also possible to support different multicast authentication schemes within one technical solution and to use the described approach only for timely critical messages, while other messages may use the typical approach verifying a message, before operating on the content. Additionally, combining solutions allows for in-time authentication as a group member, while the delayed authentication can be used to identify an individual sender.

The described approach has not been implemented, yet. Hence, performance numbers and especially performance comparisons of the different approaches cannot be delivered at this time.

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